

Computation with reaction networks

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Mathematical Modeling of Chemical Reaction Networks
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Autonomous computation in a cell

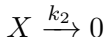
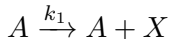
- **Goal:** Construct synthetic reaction networks that perform pre-determined task.
- Field is called “computation with chemical reaction networks”.
- Use sub-cellular substrate (eg. proteins) to devise a “chemical” computer instead of a silicon-based one.
- Tasks can be simple, eg. arithmetic or complex, eg. machine learning.

Elementary operations

- Implementing identity function.
- Suppose we want to assign a pre-determined value a to the species X .
- Think of species A as input species whose concentration a is input value.
- Think of species X as output species whose concentration x will be the output of the computation.
- **Want:** Concentration of input species never changes.
Output species converges to the correct value.

Elementary operations: identity

Reference: Buisman, Eikelder, Hilbers, Liekens: Computing algebraic functions with biochemical reaction networks



- X degrades autonomously with rate constant k_2 .
- A catalyzes production of X with rate constant k_1 .
- We do not include the resource (raw material from which X is assembled) and waste (that X breaks down into).
- Set rate constants k_1 and k_2 to 1.

$$\dot{a} = 0$$

$$\dot{x} = a - x$$

Clearly at steady state $x = a = a(0)$.

Elementary operations: identity

$$A \xrightarrow{k_1} A + X$$

$$X \xrightarrow{k_2} 0$$

$$\dot{a} = 0$$

$$\dot{x} = k_1 a - k_2 x$$

Explicit solution:

$$a(t) = a(0)$$

$$x(t) = \frac{1}{k_2} \left(k_1 a_0 - (k_1 a_0 - k_2 x_0) e^{-k_2 t} \right)$$

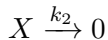
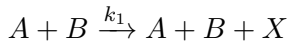
$$x(t) \xrightarrow{t \rightarrow \infty} \frac{k_1}{k_2} a_0$$

- **Note:** The convergence happens at an exponential rate.
- We implemented “multiplying by a fixed constant”.

Digital vs. Analog

- Usual silicon computers are digital.
- Boolean arithmetic and discretization are used to approximate continuous processes.
- A “chemical computer” is nonlinear and analog.
- When performing arithmetic, we are implementing discrete operations which are approximated with continuous processes.

Elementary operations: multiplication



$$\dot{a} = 0, \quad \dot{b} = 0$$

$$\dot{x} = k_1 ab - k_2 x$$

Explicit solution:

$$a(t) = a(0)$$

$$x(t) = \frac{1}{k_2} \left(k_1 a_0 b_0 - (k_1 a_0 b_0 - k_2 x_0) e^{-k_2 t} \right)$$

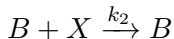
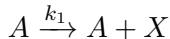
$$x(t) \xrightarrow{t \rightarrow \infty} \frac{k_1}{k_2} a_0 b_0$$

Elementary operations: division

Exercise: How would you implement division?

Elementary operations: division

Exercise: How would you implement division?



$$\dot{x} = k_1 a - k_2 b x$$

Explicit solution:

$$x(t) = \frac{1}{k_2 b_0} \left(k_1 a_0 - (k_1 a_0 - k_2 b_0 x_0) e^{-k_2 b_0 t} \right)$$

$$x(t) \xrightarrow{t \rightarrow \infty} \frac{k_1 a_0}{k_2 b_0}$$

Elementary operations: addition

Exercise: How would you implement addition?

Elementary operations: addition

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$$A \xrightarrow{1} A + X$$

$$B \xrightarrow{1} B + X$$

$$X \xrightarrow{1} 0$$

$$\dot{x} = a + b - x$$

Elementary operations: subtraction

Exercise: How would you implement subtraction?

Think first about why subtraction is trickier than all previous operations?

Elementary operations: subtraction

Exercise: How would you implement subtraction?

Think first about why subtraction is trickier than all previous operations?

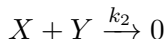
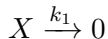
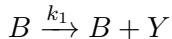
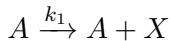
- For the previous operations, the input was 1 or 2 positive reals and the output was a positive real. Positive reals can be coded as concentrations of species.
- Applying subtraction to two positive reals can result in a negative real. How to handle this?
- Define proper subtraction (also called monus)

$$a \dot{-} b = \begin{cases} 0 & \text{if } a < b \\ a - b & \text{if } a \geq b. \end{cases}$$

- Many possibilities. Sometimes dual rail construction. One variable tracks positive part while another tracks negative part. $x = x^+ - x^-$ with $x^+, x^- > 0$.

Elementary operations: subtraction

- Non-dual rail construction.
- We need multiple dynamic (non-input) variables.



$$\dot{x} = k_1 a - k_1 x - k_2 xy$$

$$\dot{y} = k_1 b - k_2 xy$$

- Explicit solution seems difficult.
- Need nonlinear analysis (note the nonlinear term xy).

Elementary operations: subtraction

Exercise: Find the positive steady states.

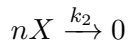
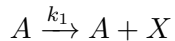
Elementary operations: subtraction

- Steady states are

$$x^* = a_0 - b_0,$$
$$y^* = \frac{k_1 b_0}{k_2(a_0 - b_0)}$$

Exercise: Calculate the Jacobian matrix at the steady state and determine its linear stability.

Elementary (unary) operation: n th root

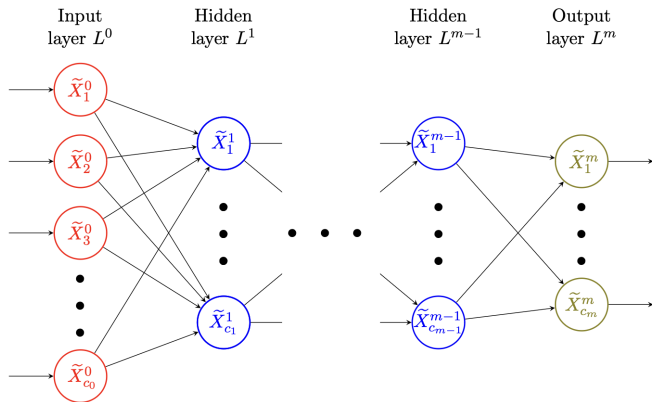


$$\dot{x} = k_1 a - k_2 x^n$$

Exercises

- 1 Show that the steady state for subtraction is exponentially stable. Does this prove that for all initial values we will have convergence to the steady state?
- 2 Some of the operations (eg. multiplication, n th root) required higher-than-bimolecular complexes. Can you modify the construction such that only bimolecular complexes are involved?

Structure of a Neural Network



Source: David F. Anderson, Badal Joshi, and Abhishek Deshpande. On reaction network implementations of neural networks, *Journal of Royal Society Interface*, Vol. 18, Issue 177, (April 2021), arXiv.

Hardwired neural network

A pair of consecutive layers $L^{\ell-1}$ and L^ℓ along with all edges between the two layers, encode a function $\psi^\ell : \mathbb{R}^{c_{\ell-1}} \rightarrow \mathbb{R}^{c_\ell}$ which is defined via

$$\psi^\ell(\mathbf{y}) = \varphi(W^\ell \mathbf{y} + \beta^\ell).$$

Taking compositions, a hardwired neural network is then simply a visual representation for the function $\Psi_{(G, \mathcal{P}, \varphi)} : \mathbb{R}^{c_0} \rightarrow \mathbb{R}_{\geq 0}^{c_m}$ defined via

$$\Psi_{(G, \mathcal{P}, \varphi)} = \psi^m \circ \psi^{m-1} \circ \dots \circ \psi^1.$$

The function φ is called activation function.

Hardwired neural network

Commonly used activation functions:

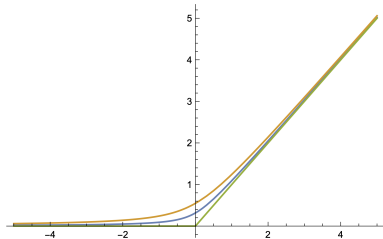
- 1 ReLU (Rectified Linear Units)

$$\varphi_0(y) = \max(0, y)$$

- 2 For $h \geq 0$,

$$\varphi_h(y) = \frac{1}{2} \left(y + \sqrt{y^2 + 4h} \right).$$

Plugging $h = 0$ in φ_h gives ReLU. φ_h is smoothed version of ReLU while being strictly monotone.



Hardwired neural network

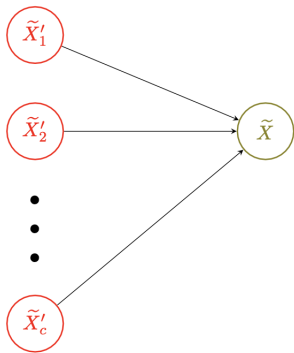
Which aspect of neural network is implemented chemically?	Chemical implementation of a single directed edge (\tilde{X}' , \tilde{X}) of the neural network	Which term results in the ODE for the species X ?
Closeness to ReLU	$H \rightarrow H + X$	h
Input \tilde{X}' and weight of the edge (\tilde{X}' , \tilde{X})	$X' + W^+ + X \rightarrow X' + W^+ + 2X$ $X' + W^- + X \rightarrow X' + W^-$	$(w^+ - w^-)x'$, where $w := w^+ - w^-$ implements the edge weight
Additive node bias of \tilde{X}	$B^+ + X \rightarrow B^+ + 2X$ $B^- + X \rightarrow B^-$	$(b^+ - b^-)x$, where $b := b^+ - b^-$ implements the node bias
q -polynomial decay Stability/convergence from ∞	$qX \rightarrow X$ ($q > 1$)	$(q - 1)x^q$

Chemical implementation of a single directed edge (\tilde{X}' , \tilde{X}) along with nodes \tilde{X}' and \tilde{X} of the neural network.

$$\frac{d}{dt}x(t) = h + ((b^+ - b^-) + (w^+ - w^-)x')x(t) - (q - 1)x(t)^q.$$

Hardwired neural network

$$\begin{aligned}\frac{d}{dt}x(t) &= h + \left((b^+ - b^-) + \sum_{i=1}^c (w_{x'_i, x}^+ - w_{x'_i, x}^-) x'_i \right) x(t) - x(t)^2 \\ &= h + \rho_x x(t) - x(t)^2\end{aligned}$$



Step two: node \tilde{X} along with all its c inputs.

Thank you!